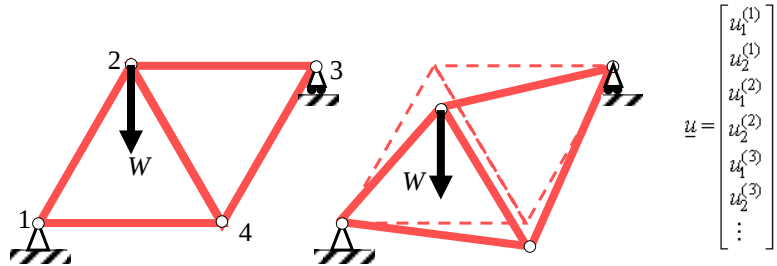
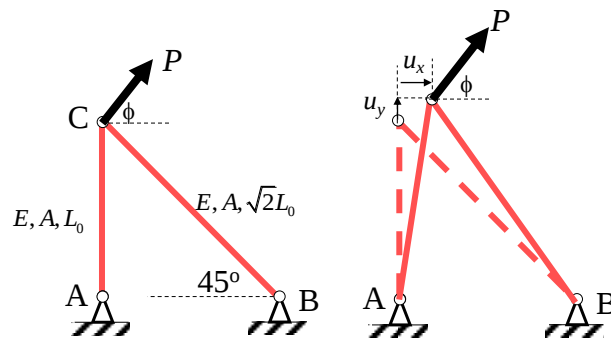


Stiffness Formulation of Truss analysis: forces and deflections



Fundamental Unknowns
are Nodal (joint) Displacements

Example



Method of Joints:

$$\sum F_{Cx} = F_{BC} / \sqrt{2} + P \cos \phi = 0$$

$$\sum F_{Cy} = -F_{AC} - F_{BC} / \sqrt{2} + P \sin \phi = 0$$

$$F_{AC} = P(\sin \phi + \cos \phi), F_{BC} = -P\sqrt{2} \cos \phi$$

Stiffness Matrix

- Deflection in AC $\delta_{AC} = u_y$
- Force in AC $F_{AC} = \frac{EA}{L_0} u_y$
- Deflection in BC $\delta_{BC} = \frac{1}{\sqrt{2}} (u_y - u_x)$
- Force in BC: $F_{BC} = \frac{EA}{2L_0} (u_y - u_x)$
- Matrix Equation:
$$\frac{EA}{2\sqrt{2}L_0} \begin{bmatrix} 1 & -1 \\ -1 & 1 + 2\sqrt{2} \end{bmatrix} \begin{bmatrix} u_x \\ u_y \end{bmatrix} = \begin{bmatrix} P \cos \phi \\ P \sin \phi \end{bmatrix}$$

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```

> restart;with(linalg):
> K:=(EA/L/2/sqrt(2))*matrix([[1,-1],[-1,2*sqrt(2)+1]]);

```

$$K := \frac{1}{4} \frac{EA \sqrt{2}}{L} \begin{bmatrix} 1 & -1 \\ -1 & 2\sqrt{2}+1 \end{bmatrix}$$

```

> Pv:=vector([P*cos(phi),P*sin(phi)]);

```

$$Pv := [P \cos(\phi), P \sin(\phi)]$$

```

> u:=linsolve(K,Pv);

```

$$u := \left[\frac{P L (\sin(\phi) + \cos(\phi) + 2\sqrt{2} \cos(\phi))}{EA}, \frac{P L (\sin(\phi) + \cos(\phi))}{EA} \right]$$

```

> M:=(EA/L)*matrix([[0,1],[-1/2,1/2]]);

```

$$M := \frac{EA}{L} \begin{bmatrix} 0 & 1 \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

```

> forces:=multiply(M,u);

```

$$forces := \left[P (\sin(\phi) + \cos(\phi)), -\frac{1}{2} P (\sin(\phi) + \cos(\phi) + 2\sqrt{2} \cos(\phi)) + \frac{1}{2} P (\sin(\phi) + \cos(\phi)) \right]$$

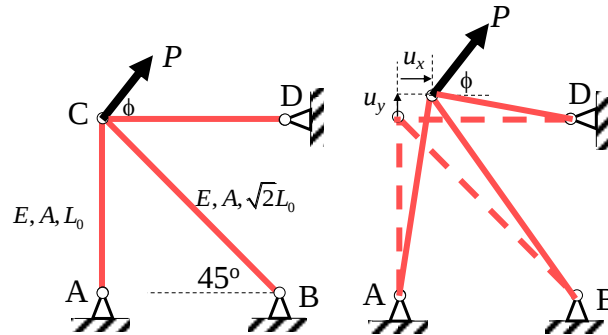
```

> simplify(forces);

```

$$[P (\sin(\phi) + \cos(\phi)), -P \sqrt{2} \cos(\phi)]$$

Works for Statically indeterminate too.



```

Maple 11 - [stiffness ex1.mws - [Server 1]]
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[Icons]
[Icons]
> K2 := (EA/L/2/sqrt(2)) * matrix([[2*sqrt(2)+1, -1], [-1, 2*sqrt(2)+1]]);
                                     EA*sqrt(2) [ 2*sqrt(2)+1  -1 ]
                                     K2 = 1/4 [ -1  2*sqrt(2)+1 ]
                                     L
> u2 := linsolve(K2, Pv);
                                     1 P L (sin(phi) + cos(phi) + 2*sqrt(2) cos(phi)) 1 sqrt(2) P L (4 sin(phi) + sqrt(2) cos(phi) + sqrt(2) sin(phi))
                                     2 EA (sqrt(2)+1) 4 EA (sqrt(2)+1)
> M2 := (EA/L) * matrix([[0, 1], [-1/2, 1/2], [-1, 0]]);
                                     EA [ 0  1 ]
                                     [-1/2  1/2 ]
                                     M2 = -1 [ -1  0 ]
                                     L
> forces := multiply(M2, u2);
forces = [ 1 sqrt(2) P (4 sin(phi) + sqrt(2) cos(phi) + sqrt(2) sin(phi)) 1 P (sin(phi) + cos(phi) + 2 sqrt(2) cos(phi)) 1 sqrt(2) P (4 sin(phi) + sqrt(2) cos(phi) + sqrt(2) sin(phi))
          4 sqrt(2)+1 4 sqrt(2)+1 8 sqrt(2)+1
          1 P (sin(phi) + cos(phi) + 2 sqrt(2) cos(phi)) ]
          2 sqrt(2)+1
> simplify(forces);
          [ 1 sqrt(2) P (4 sin(phi) + sqrt(2) cos(phi) + sqrt(2) sin(phi)) 1 P sqrt(2) (-sin(phi) + cos(phi)) 1 P (sin(phi) + cos(phi) + 2 sqrt(2) cos(phi)) ]
          4 sqrt(2)+1 2 sqrt(2)+1 2 sqrt(2)+1

```