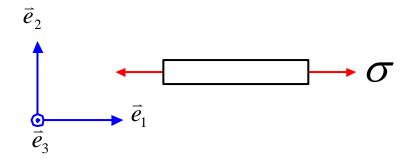
Stress in a solid

Examples of common stress states:

1. Uniaxial stress

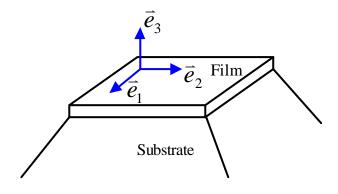


$$\underline{\sigma} = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Principal stresses: $\sigma_{I} = \sigma$, $\sigma_{II} = \sigma_{III} = 0$

Principal directions: \vec{e}_1 , \vec{e}_2 , \vec{e}_3 (\vec{e}_2 , \vec{e}_3 can be replaced by any direction in 2-3 plane)

2. Biaxial stress

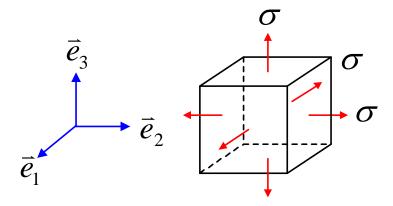


$$\underline{\sigma} = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Principal stresses: $\sigma_{I} = \sigma_{II} = \sigma$, $\sigma_{III} = 0$

Principal directions: \vec{e}_1 , \vec{e}_2 , \vec{e}_3 (\vec{e}_1 , \vec{e}_2 can be replaced by any direction in 1-2 plane)

3. Hydrostatic stress

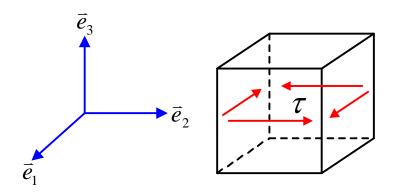


$$\underline{\sigma} = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{bmatrix} = \sigma \underline{I}$$

Principal stresses: $\sigma_I = \sigma_{II} = \sigma_{III} = \sigma$

Principal directions: any direction (since there is no shear stress on any cut plane)

4. Pure shear



$$\underline{\sigma} = \begin{bmatrix} 0 & \tau & 0 \\ \tau & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \tau \, \vec{e}_1 \otimes \vec{e}_2 + \tau \, \vec{e}_2 \otimes \vec{e}_1$$

Principal stresses:

$$\begin{bmatrix} 0 & \tau & 0 \\ \tau & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \lambda \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} \Rightarrow \begin{bmatrix} -\lambda & \tau & 0 \\ \tau & -\lambda & 0 \\ 0 & 0 & -\lambda \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = 0$$

For nontrivial solution of n_i ,

$$\det \begin{bmatrix} -\lambda & \tau & 0 \\ \tau & -\lambda & 0 \\ 0 & 0 & -\lambda \end{bmatrix} = 0,$$

which indicates

$$-\lambda(\lambda^2-\tau^2)=0 \Rightarrow \lambda=\tau,0,-\tau$$

Following the convention $\sigma_{I}>\sigma_{II}>\sigma_{II}$, we can write

$$\sigma_I = \tau$$
, $\sigma_{II} = 0$, $\sigma_{III} = -\tau$

Principal directions:

Principal direction I ($\sigma_I = \tau$):

$$\begin{bmatrix} -\tau & \tau & 0 \\ \tau & -\tau & 0 \\ 0 & 0 & -\tau \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = 0$$

That is

$$n_1 = n_2, \quad n_3 = 0$$

In addition, $n_1^2 + n_2^2 + n_3^2 = 1$ (because \vec{n} is a unit vector).

$$\begin{cases} n_1 = \pm \frac{1}{\sqrt{2}} \\ n_2 = \pm \frac{1}{\sqrt{2}} \\ n_3 = 0 \end{cases}$$

Therefore: $\vec{n}_I = \pm \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0\right)$

Principal direction $II (\sigma_{II} = 0)$:

$$\begin{bmatrix} 0 & \tau & 0 \\ \tau & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = 0$$

That is

$$n_1 = n_2 = 0$$

In addition, $n_1^2 + n_2^2 + n_3^2 = 1$ (\vec{n} is a unit vector).

$$\begin{cases} n_1 = 0 \\ n_2 = 0 \\ n_3 = \pm 1 \end{cases}$$

Therefore: $\vec{n}_{II} = \pm (0, 0, 1)$

Principal direction $\it III$ ($\sigma_{\it III} = -\tau$):

$$\begin{bmatrix} \tau & \tau & 0 \\ \tau & \tau & 0 \\ 0 & 0 & \tau \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = 0$$

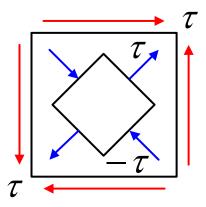
That is

$$n_1 = -n_2$$
, $n_3 = 0$

In addition, $n_1^2 + n_2^2 + n_3^2 = 1$ (\vec{n} is a unit vector).

$$\begin{cases} n_1 = \pm \frac{1}{\sqrt{2}} \\ n_2 = \mp \frac{1}{\sqrt{2}} \\ n_3 = 0 \end{cases}$$

Therefore: $\vec{n}_{III} = \pm \left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0\right)$



Deviatoric stress tensor

An arbitrary stress tensor can be written in

$$\sigma_{ij} = \frac{1}{3}\sigma_{kk}\delta_{ij} + \sigma_{ij}$$

Define $\sigma_h = \frac{1}{3}\sigma_{kk} = \frac{1}{3}(\sigma_I + \sigma_{II} + \sigma_{III})$, which represents the hydrostatic part of the stress.

$$\sigma_{ij}^{'} = \sigma_{ij} - \sigma_h \delta_{ij}$$

Let $i \rightarrow j$,

$$\sigma_{jj}' = \sigma_{jj} - \sigma_h \delta_{jj} = \sigma_{jj} - 3\sigma_h = 0$$

i.e. $\operatorname{trace}(\sigma_{ij}) = \sigma_{11} + \sigma_{22} + \sigma_{33} = 0$.

 σ_{ij} has 3 invariants: $\sigma_{kk} = 0$, $\sigma_{ij} \sigma_{ij}$, $\det(\sigma_{ij})$

Among the 3 invariants of σ_{ij} , σ_{ij} σ_{ij} is related to the von Mises stress which plays an important role in modeling plastic yielding).

von Mises stress

Consider the case of uniaxial tension with principal stresses:

$$\sigma_I = \sigma$$
, $\sigma_{II} = \sigma_{III} = 0$

The stress tensor in the principal directions is

$$\underline{\sigma} = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

The principal stresses of the deviatoric stress tensor are

$$\sigma_{I} = \frac{2}{3}\sigma$$
, $\sigma_{II} = \sigma_{III} = -\frac{1}{3}\sigma$

Therefore

$$\sigma_{ij} \sigma_{ij} = \sigma_{I}^{2} + \sigma_{II}^{2} + \sigma_{III}^{2} = \frac{2}{3} \sigma^{2}$$

i.e.

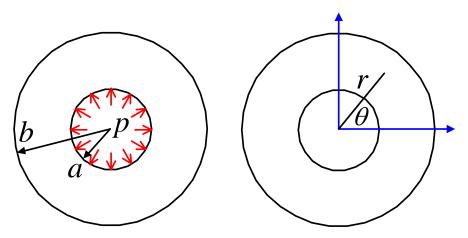
$$\sqrt{\frac{3}{2}\sigma_{ij}^{'}\sigma_{ij}^{'}} = \sigma$$

von Mises stress is defined as $\sigma_e = \sqrt{\frac{3}{2}\sigma_{ij}^{'}\sigma_{ij}^{'}}$ such that $\sigma_e = \sigma$ in the case of uniaxial tension.

Traction BC's for BVPs in solid mechanics

The Cauchy relationship between stress and traction serves as a basis to express traction boundary conditions in terms of the relevant stress components. We consider two examples

Example 1:



$$\vec{t} = \underline{\sigma} \vec{e}_r = 0$$
 @ $r = b$ (traction free at $r = b$)

$$\vec{t} = \underline{\sigma}(-\vec{e}_r) = p\vec{e}_r @ r = a$$

In Polar coordinates,

@ r = b:

$$\sigma_{rr} = \vec{e}_r \cdot \underline{\sigma} \, \vec{e}_r = 0 \; , \; \sigma_{r\theta} = \vec{e}_\theta \cdot \underline{\sigma} \, \vec{e}_r = 0$$

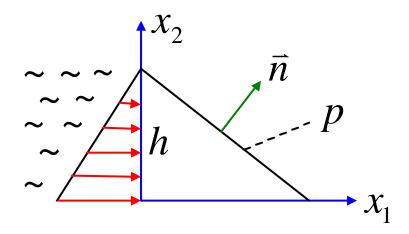
@ r = a:

$$\sigma_{rr} = \vec{e}_r \cdot \underline{\sigma} \, \vec{e}_r = -p \,, \ \sigma_{r\theta} = \vec{e}_\theta \cdot \underline{\sigma} \, \vec{e}_r = 0$$

Therefore, the BCs for the above problem are often expressed as

$$\begin{cases} \sigma_{rr} = -p & \sigma_{r\theta} = 0 & r = a \\ \sigma_{rr} = 0 & \sigma_{r\theta} = 0 & r = a \end{cases}$$

Example 2:



$$\vec{t} = \underline{\sigma}(-\vec{e}_1) = \rho g(h - x_2)\vec{e}_1 @ x_1 = 0$$

$$\vec{t} = \sigma \vec{n} = 0$$
 @ p plane

@
$$x_1 = 0$$

$$\sigma_{11} = \vec{e}_1 \cdot \underline{\sigma} \, \vec{e}_1 = -\rho \, g(h - x_2)$$

$$\sigma_{12} = \vec{e}_2 \cdot \underline{\sigma} \, \vec{e}_1 = 0$$

Maximum and minimum normal & shear stresses in a solid

We want to show that, given principal stresses $\sigma_I > \sigma_{II} > \sigma_{III}$, the maximum and minimum normal and shear stresses in a solid have the following simple results:

$$\max(\sigma_n) = \sigma_I, \min(\sigma_n) = \sigma_{III}$$

$$\max(\sigma_s) = \frac{\sigma_I - \sigma_{III}}{2}, \min(\sigma_s) = 0$$

Proof:

Choose base vectors in the principal directions,

$$\underline{\sigma} = \begin{bmatrix} \sigma_I & 0 & 0 \\ 0 & \sigma_{II} & 0 \\ 0 & 0 & \sigma_{III} \end{bmatrix}$$

The traction on an arbitrary plane with normal \vec{n} (note that $n_1^2 + n_2^2 + n_3^2 = 1$) is

$$\vec{t} = \sigma \vec{n}$$

The normal stress on that plane is

$$\sigma_n = \vec{n} \cdot \vec{t} = \vec{n} \cdot \sigma \, \vec{n} = \sigma_I n_1^2 + \sigma_{II} n_2^2 + \sigma_{III} n_3^2$$

Introduce Lagrangian multiplier λ ,

$$F = \sigma_I n_1^2 + \sigma_{II} n_2^2 + \sigma_{III} n_3^2 - \lambda (n_1^2 + n_2^2 + n_3^2)$$

$$\frac{\partial F}{\partial n_1} = 0 \Rightarrow 2\sigma_1 n_1 - 2\lambda n_1 = 0 \tag{1}$$

$$\frac{\partial F}{\partial n_2} = 0 \Rightarrow 2\sigma_{II} n_2 - 2\lambda n_2 = 0 \tag{2}$$

$$\frac{\partial F}{\partial n_3} = 0 \Rightarrow 2\sigma_{III} n_3 - 2\lambda n_3 = 0 \tag{3}$$

Case 1: $n_1 \neq 0$, $n_2 \neq 0$, $n_3 \neq 0$

From the equations (1)-(3):

$$\sigma_I = \sigma_{II} = \sigma_{III} = \lambda$$
,

which is contradictory to our assumption $\sigma_I > \sigma_{II} > \sigma_{III}$. (The cases when some of the principal stresses are equal are quite simple and can be treated separately.)

Case 2: 2 of n_1 , n_2 , n_3 are not zero

If
$$n_1 = 0$$
, $n_2 \neq 0$, $n_3 \neq 0$

$$2\sigma_n n_2 - 2\lambda n_2 = 0$$

$$2\sigma_{III}n_3 - 2\lambda n_3 = 0$$

$$n_2^2 + n_3^2 = 1$$

The solution is $\sigma_{II}=\sigma_{III}=\lambda$, again contradictory to our assumption $\sigma_{I}>\sigma_{II}>\sigma_{III}$.

Similarly, $(n_2=0\,,\ n_1\neq 0\,,\ n_3\neq 0\,)$ and $(n_3=0\,,\ n_1\neq 0\,,\ n_2\neq 0\,)$ also lead to solutions contradictory to our assumption.

Case 3: 2 of n_1 , n_2 , n_3 are zero

If
$$n_1 \neq 0$$
, $n_2 = n_3 = 0$, $\vec{n} = \pm (1, 0, 0)$

If
$$n_2 \neq 0$$
, $n_1 = n_3 = 0$, $\vec{n} = \pm (0, 1, 0)$

If
$$n_3 \neq 0$$
, $n_1 = n_2 = 0$, $\vec{n} = \pm (0, 0, 1)$

These are just principal directions. Therefore,

$$\max(\sigma_n) = \sigma_I$$
, $\min(\sigma_n) = \sigma_{III} (\sigma_I > \sigma_{II} > \sigma_{III})$

