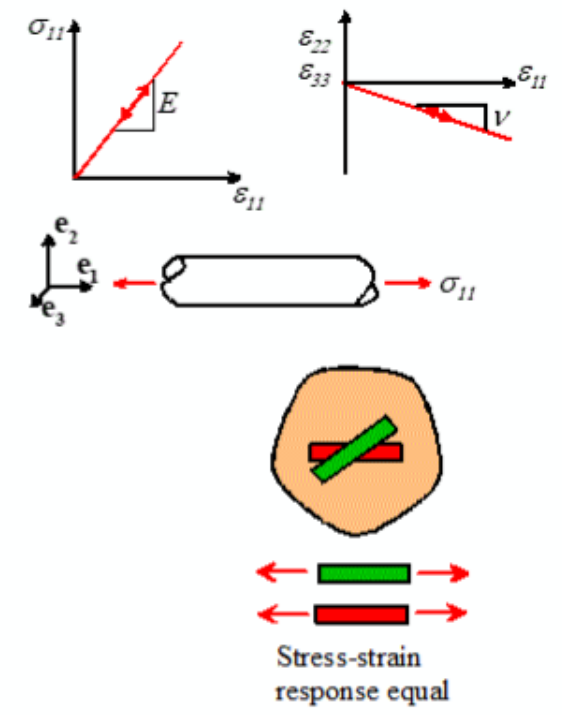


Review

Stress-Strain-Temperature relations for elastic solids

Assumptions:

1. Small deformations
2. Isotropic material
3. Strain linearly related to stress / temp
4. Perfectly reversible



Matrix form for stress-strain law (3D)

$$\begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{bmatrix} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & -\nu & 0 & 0 & 0 \\ -\nu & 1 & -\nu & 0 & 0 & 0 \\ -\nu & -\nu & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2(1+\nu) & 0 & 0 \\ 0 & 0 & 0 & 0 & 2(1+\nu) & 0 \\ 0 & 0 & 0 & 0 & 0 & 2(1+\nu) \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} + \alpha \Delta T \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu & 0 & 0 & 0 \\ \nu & 1-\nu & \nu & 0 & 0 & 0 \\ \nu & \nu & 1-\nu & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{(1-2\nu)}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{(1-2\nu)}{2} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{(1-2\nu)}{2} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{bmatrix} - \frac{E\alpha\Delta T}{1-2\nu} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

7.4 Anisotropic Materials

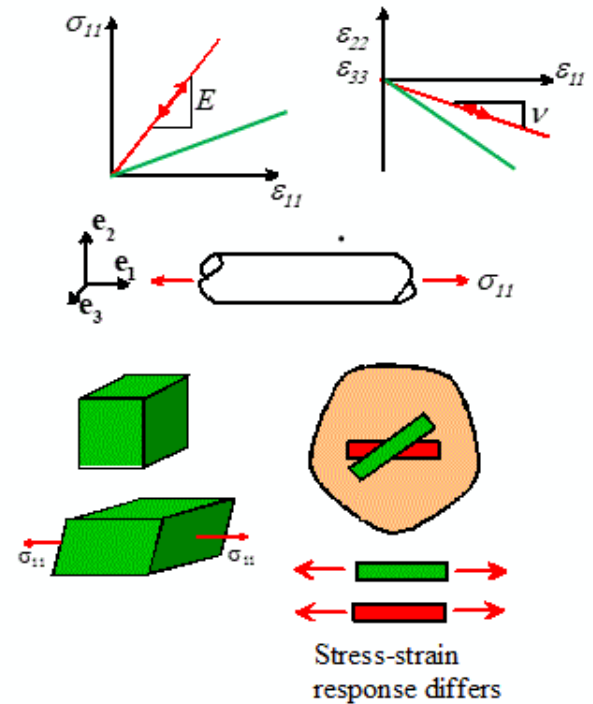
Anisotropy means

- (1) Response depends on orientation of specimen wrt to material
- (2) Tensile stress may induce shear strain

Options in ABAQUS:

- (1) General
- (2) Orthotropic

Examples: composites ; wood ; single xtals



General anisotropic σ - ϵ relations

$$\underline{\sigma} = [C] (\underline{\epsilon} - \underline{\alpha} \Delta T)$$

$$\underline{\sigma} = [\sigma_{11}, \sigma_{22}, \sigma_{33}, \sigma_{12}, \sigma_{13}, \sigma_{23}]$$

$$\underline{\epsilon} = [\epsilon_{11}, \epsilon_{22}, \epsilon_{33}, 2\epsilon_{12}, 2\epsilon_{13}, 2\epsilon_{23}]$$

Now $[C]$ is a nonzero symmetric 6×6 matrix

$$[C] = \begin{bmatrix} D_{1111} & D_{1122} & D_{1133} & D_{1112} & \text{etc} \\ & D_{2222} & & & \\ \text{Sym} & & & & \end{bmatrix}$$

D_{ijke} is the same as C_{ijke} (4^{th} order tensor)
Some books use $D_{1111} = C_{11}$ $D_{1122} = C_{12}$ etc

$$\underline{\alpha} = [\alpha_{11} \quad \alpha_{22} \quad \alpha_{33}, \quad \underbrace{2\alpha_{12}}_{\text{2 may or may not be used}} \quad 2\alpha_{13} \quad 2\alpha_{23}]$$

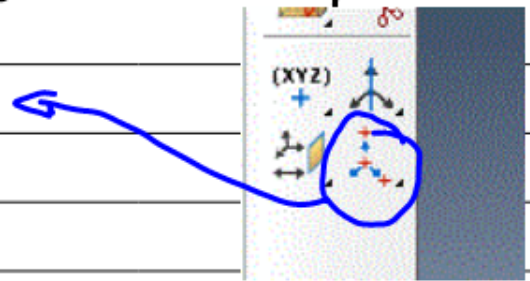
Elastic						Expansion				
Type:	Anisotropic					Type:	Anisotropic			
<input type="checkbox"/> Use temperature-dependent data						<input type="checkbox"/> Use user subroutine UEXPAN				
Number of field variables:	0					Reference temperature:	0			
Moduli time scale (for viscoelasticity):	Long-term					<input type="checkbox"/> Use temperature-dependent data				
<input type="checkbox"/> No compression						Number of field variables:	0			
<input type="checkbox"/> No tension						Data				
Data							alpha11	alpha22	alpha33	alpha12
1	D1111	D1122	D2222	D1133	D2233	D3333	1			

ABAQUS menus : enter numbers (2) elastic consts !)

Note values of Dijke depend on basis for σ , ϵ

In ABAQUS you can specify the orientation of material axes (basis for σ - ϵ law)

- (1) Create a local coordinate system
- (2) Assign material orientation to part



Orthotropic materials

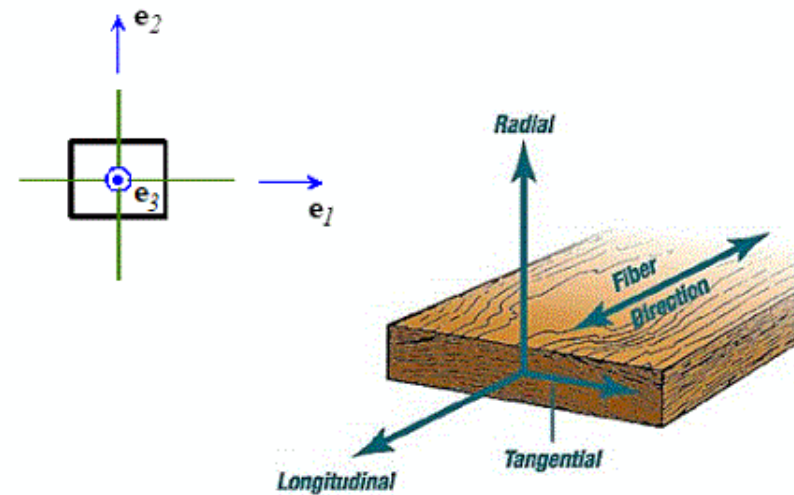
Orthotropic materials have 3 symmetry planes

if we choose $\{e_1, e_2, e_3\}$ to be perpendicular to symmetry planes then $[C]$ has form

$$[C] = \begin{bmatrix} D_{1111} & D_{1122} & D_{1133} & 0 & 0 & 0 \\ & D_{222} & D_{2233} & 0 & 0 & 0 \\ & & D_{3333} & 0 & 0 & 0 \\ & & & D_{1212} & 0 & 0 \\ & & & 0 & D_{1313} & 0 \\ & & & 0 & 0 & D_{2323} \end{bmatrix}$$

also $\alpha = [\alpha_{11} \alpha_{22} \alpha_{33} 0 0 0]$

Will need to specify orientation wrt part

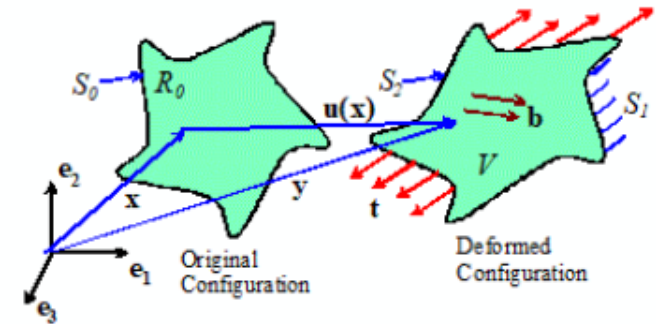


8) Solving static boundary value problems for linear elastic solids

Assume: (1) Small deformations
(2) Elastic, isotropic material

Given: Body force \underline{b}
Temperature ΔT

Boundary loading : either $\underline{u} = \underline{u}^*$ given on S_1
 \underline{t} given on S_2
(or mixed \underline{t} , \underline{u} components)



Find: $[\underline{u}, \underline{\epsilon}, \underline{\sigma}]$ satisfying

(1) Strain-displacement

$$\underline{\epsilon} = (\nabla \underline{u} + (\nabla \underline{u})^T) / 2$$

(2) Material law

$$\underline{\sigma} = \underline{C} (\underline{\epsilon} - \alpha \Delta T)$$

(3) Static equilibrium

$$\nabla \cdot \underline{\sigma} + \rho \underline{b} = \underline{0} \quad (\text{statics})$$

(4) Boundary conditions

$$\underline{u} = \underline{u}^* \text{ on } S_1 \quad \underline{n} \cdot \underline{\sigma} = \underline{t} \text{ on } S_2$$

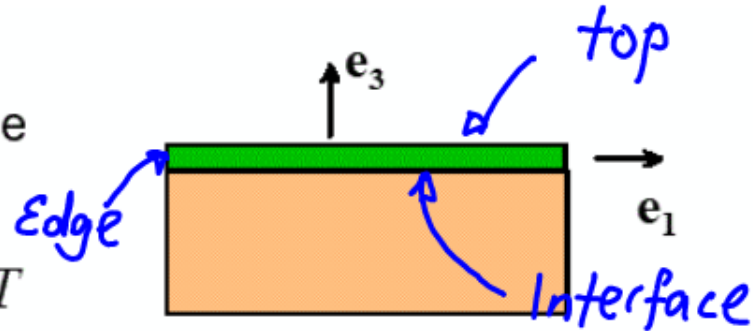
8.1 Solving simple problems (approximately) using physical reasoning

Example: Film, elastic constants (E, ν, α) on a large rigid substrate with $\alpha = 0$

Initially stress free, then heated to temp ΔT

Find stress in film and strain energy density

(Focus on behavior away from edges)



- Observations:
- (1) Substrate is rigid $\Rightarrow \underline{u} = 0$ in substrate
 - (2) Top and edge are traction free
 - (3) Film remains bonded \Rightarrow film & substrate have same \underline{u} at interface

Boundary Conditions

$$(a) \text{ Top } \underline{n} \sigma = \underline{0} \Rightarrow [0 \ 0 \ 1] \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ & \sigma_{22} & \sigma_{23} \\ & & \sigma_{33} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \sigma_{33} = 0 \quad \sigma_{13} = 0 \quad \sigma_{23} = 0 \quad (1)$$

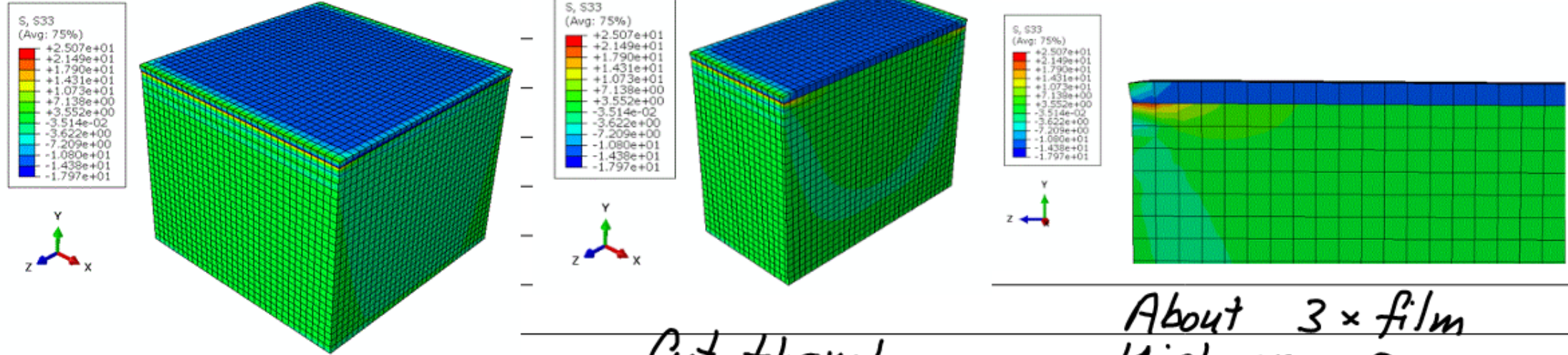
$$\text{Edges } \underline{n} = [1 \ 0 \ 0] \text{ eg } \Rightarrow \sigma_{11} = \sigma_{12} = \sigma_{13} = 0$$

$$(b) \text{ Interface } \quad U_1(x_1, x_2, 0) = U_2(x_1, x_2, 0) \\ = U_3(x_1, x_2, 0) = 0$$

$$\text{Hence } \epsilon_{11} = \partial U_1 / \partial x_1 = 0 \quad \epsilon_{22} = \partial U_2 / \partial x_2 = 0 \\ \epsilon_{12} = (\partial U_1 / \partial x_2 + \partial U_2 / \partial x_1) / 2 = 0$$

Condition (1) \Rightarrow plane stress state \Leftrightarrow surface

FEA solution



Away from edges stress is uniform

Cut through center

About 3x film thicknesses away from edge σ is uniform

Assume $[\sigma, \epsilon]$ are constant

$$\Rightarrow \nabla \cdot \underline{\underline{\sigma}} + \underline{\underline{b}} = \underline{\underline{0}} \text{ automatically } \nabla \cdot \sigma = 0 !$$

Satisfy BCs : we must have plane stress

σ - ϵ relations for plane stress

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{12} \end{bmatrix} = \frac{E}{(1-\nu^2)} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & (1-\nu)/2 \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ 2\epsilon_{12} \end{bmatrix} - \frac{E\alpha\Delta T}{(1-\nu)} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\epsilon_{33} = -\frac{\nu}{E}(\sigma_{11} + \sigma_{22}) + \alpha\Delta T = 0$$

\Rightarrow

$$\sigma_{11} = \sigma_{22} = -\frac{E\alpha\Delta T}{1-\nu}$$

All other $\sigma_{ij} = 0$

$$\epsilon_{33} = \frac{(1+\nu)}{(1-\nu)} \alpha\Delta T$$

all other $\epsilon_{ij} = 0$

Strain energy density $U = \frac{1}{2} \sigma_{ij} \epsilon_{ij}^e$

$$\epsilon_{ij}^e = \epsilon_{ij} - \alpha \sigma_{ij} \Delta T \Rightarrow \epsilon_{11}^e = \epsilon_{22}^e = -\alpha\Delta T$$

$$U = \frac{1}{2} \left\{ \sigma_{11} \epsilon_{11}^e + \sigma_{22} \epsilon_{22}^e \right\} = \frac{E}{(1-\nu)} (\alpha\Delta T)^2$$

Typical values

$$E \sim 100 \text{ GPa}$$

$$\alpha \sim 10^{-5} \text{ K}^{-1}$$

$$\nu \sim 0.3$$

$$\Delta T \sim 100^\circ \text{C}$$

$$\sigma_{11} \sim 100 \text{ MPa} \quad \text{quite large!}$$

$$U \sim 0.1 \text{ MJ/m}^3$$

for comparison energy in specific
heat capacity 400 MJ/m^3

8.2 Spherically symmetric solutions

Consider spherical shell $a < R < b$

Given : Radial body force $b(R) \underline{e}_R$
Temp $\Delta T(R)$

Either pressure p_a, p_b on
 $R = a, b$

or radial displacement $U_R(a) = U_a^* \quad U_R(b) = U_b^*$

Assume radial displacement field $\underline{U} = U_R(R) \underline{e}_R$

Solve for $[U_R(R), \epsilon, \sigma]$

