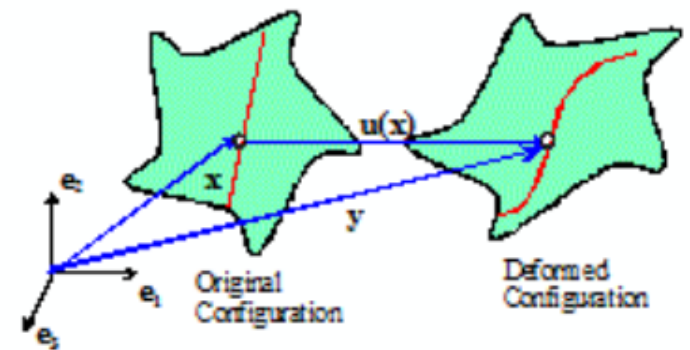


# EN2340 2017 Computational methods in solids

## 2) Overview of FEA in solids

- FEA is a general method for finding approx solutions to a PDE
- In solid mechanics our goal is to calculate a displacement field



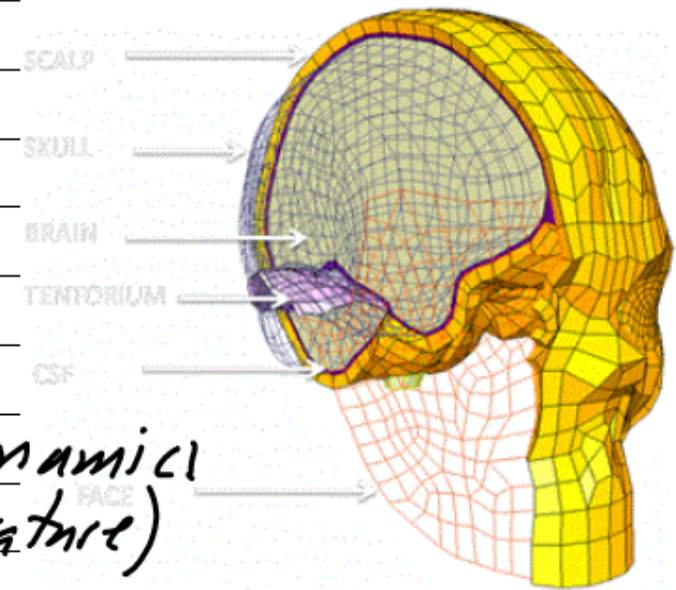
$$\underline{u}(\underline{x}, t) = \underline{y}(\underline{x}, t) - \underline{x}$$

- Given:
- (1) Shape of solid
  - (2) Constitutive model, properties
  - (3) Initial conditions, Loading

- Governing equation:  $\underline{F} = \underline{0}$  ;  $\underline{F} = m \underline{a}$

## Setting up an FEA problem

- Specify:
- (1) Geometry : Mesh
  - (2) Material model
  - (3) Contact & interfaces
  - (4) Loading, prescribed BCs
  - (5) Initial conditions for dynamics
  - (6) Other fields (eg temperature)
  - (7) Output variables

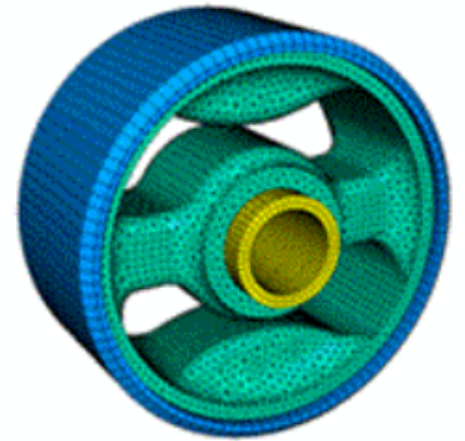


## Solution procedure:

- (1) Static or dynamics
- (2) Linear, or nonlinear
- (3) Account for large shape changes  
(NLGEOM)
- (4) Special procedures - buckling, fracture etc

## 2.1 Finite element mesh

- 3D: subdivide solid into sub-volumes



- 2D: subdivide area

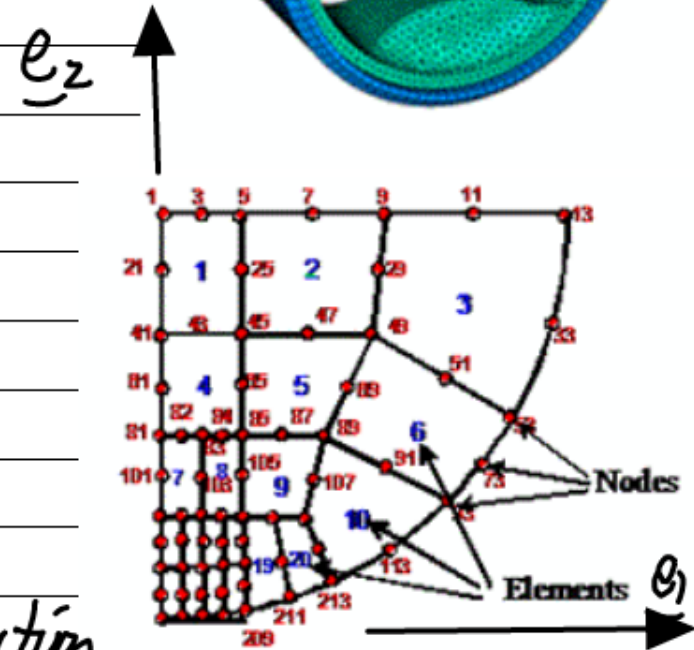
3 types: Plane stress  $\sigma_{3i} = 0$

Plane strain

$$\underline{u} = u_\alpha(x_1, x_2) \underline{e}_\alpha$$

Axisymmetry

$\underline{e}_z$  is axis of revolution  
in ABAQUS



Other reduced-order models exist

### 2.1.1 Nodes : Discrete points in solid

- Properties :
  - (1) Integer identifier
  - (2) Coord
  - (3) Degrees of freedom
    - always includes displacements
    - some special elements have rotational DOF
  - (4) Field variables

### 2.1.2 Elements : sub-divide solid

- Properties :
  - (1) Nodes on element  
"Connectivity"
  - (2) Integration points - special points in element
  - (3) Interpolation scheme

