

HW 7 Solutions ENEN 0040 2015

(40 pts)

1.1. (3 pts)

$$I_{\text{DISK}} = \frac{1}{2} m (L/4)^2$$

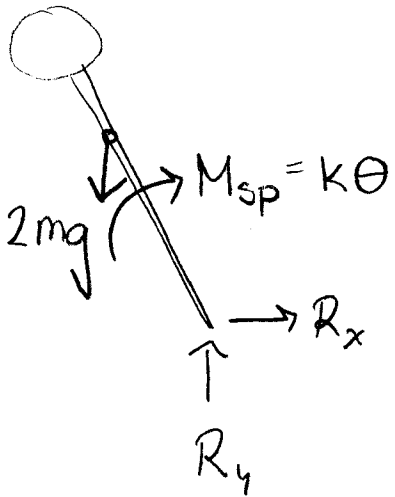
$$I_{\text{DISK}, A} = \frac{1}{2} m (L/4)^2 + m (L + L/4)^2 = 51 mL^2/32$$

$$I_{\text{ROD}} = \frac{1}{12} mL^2$$

$$I_{\text{ROD}, A} = \frac{1}{12} mL^2 + m (L/2)^2 = \frac{1}{3} mL^2$$

$$I_A = I_{\text{DISK}} + I_{\text{ROD}} = 185/96 mL^2$$

1.2.
(4 pts)

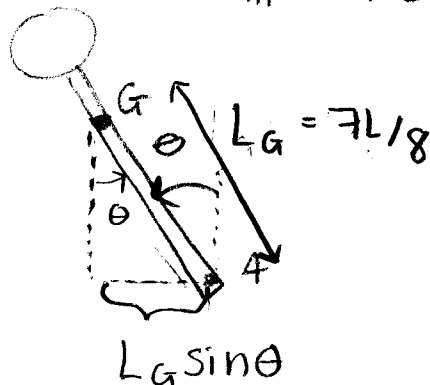


$$\sum F_x = R_x = m a_{Gx}$$

$$\sum F_y = R_y - mg = m a_{Gy}$$

$$\sum M_A = -M_{sp} + 2mg L_G \sin \theta = I_A \alpha$$

$$\sum M_A = -k\theta + 2mg \frac{7L}{8} \sin \theta = I_A \alpha$$



1.3.

(3 pts)
$$-k\theta + 2mg \frac{7L}{8} \sin \theta = \frac{185}{96} mL^2 \cdot \ddot{\theta}$$

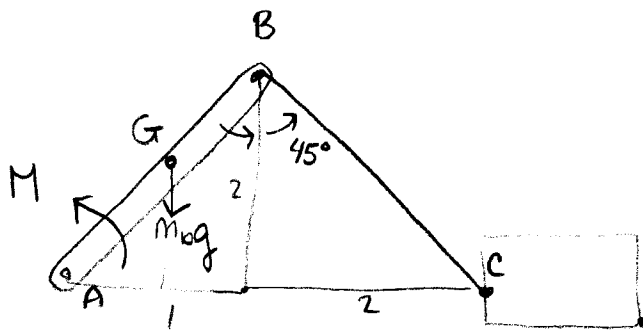
simplifying & $\sin \theta \sim \theta$

$$-k\theta + 2mg \frac{7L}{8} \cdot \theta = \frac{185}{96} mL^2 \ddot{\theta}$$

$$\frac{185}{96} mL^2 \ddot{\theta} + (2mg \frac{7L}{8} \theta - k\theta) = 0$$

$$\omega_n \approx \sqrt{\frac{\frac{7mgL}{8} \theta - k\theta}{(185/96) mL^2}}$$

2.1 (7 pts)



geometry

$$\underline{r}_{B/A} = 1\hat{i} + 2\hat{j}$$

$$\underline{r}_{C/B} = 2\hat{i} - 2\hat{j}$$

Tension mag. T , direction $\underline{e}_T = \frac{2\hat{i} - 2\hat{j}}{\sqrt{8}}$

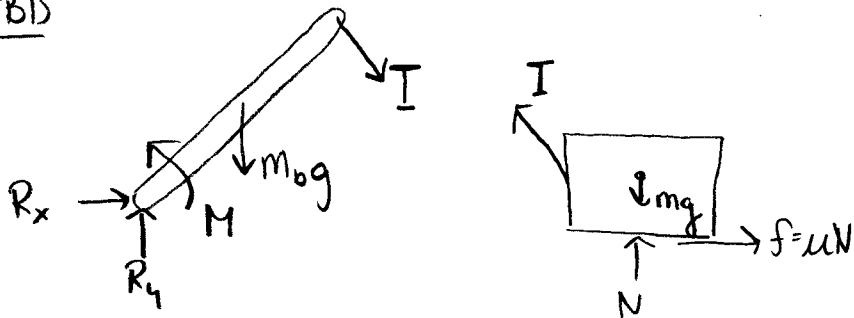
$$\underline{e}_T = \frac{\hat{i} - \hat{j}}{\sqrt{2}}$$

$$\underline{I} = T\underline{e}_T$$

$$I_A = I_G + m_b(L/2)^2, \quad L = \sqrt{5}$$

$$I_A = \frac{1}{3}m_b L^2$$

FBD



EOM

$$R_x + \frac{T\sqrt{2}}{2} = m_b a_{xG}$$

$$R_y - m_b g - \frac{T\sqrt{2}}{2} = m_b a_{yG}$$

$$M - \underbrace{m_b g \frac{L}{2} \cos 63.4^\circ}_{\hat{k} \text{ moment caused by } m_b g} + \underbrace{(\underline{r}_{B/A} \times \underline{I})}_{\hat{k} \text{ moment caused by } \underline{I}} = I_A \alpha_{AB}$$

\hat{k} moment caused by $m_b g$

\hat{k} moment caused by \underline{I}
 $= -\frac{3}{\sqrt{2}}T$

$$M - m_b g \frac{L}{2} \cos 63.4^\circ - \frac{3}{\sqrt{2}}T = I_A \alpha_{AB} \quad (2)$$

EOM (crate)

$$-mg + N + T\sqrt{2}/2 = 0$$

$$-T\sqrt{2}/2 = m_c a_{cx} \quad (1)$$

Kinematics

$$\underline{a}_B = \alpha_{AB} \times \underline{r}_{B/A} = -2\alpha_{AB}\hat{i} + \alpha_{AB}\hat{j}$$

$$\underline{a}_C = \underline{a}_B + \alpha_{BC} \times \underline{r}_{C/B} = -2\alpha_{AB}\hat{i} + \alpha_{AB}\hat{j} + 2\alpha_{BC}\hat{i} + 2\alpha_{BC}\hat{j}$$

constraint $a_{cy} = 0 \Rightarrow \alpha_{BC} = -1/2 \alpha_{AB}$

$$a_{cx} = -3\alpha_{AB} \quad (3) \quad \text{solving (1), (2) \& (3)}$$

$$a_{cx} = -2.26 \text{ m/s}^2$$

$$\alpha_{AB} = 0.75 \text{ rad/s}^2$$

2.2. (3 pts)

$$\frac{T\sqrt{2}}{2} + N - m_c g = 0$$

New eom
for crate

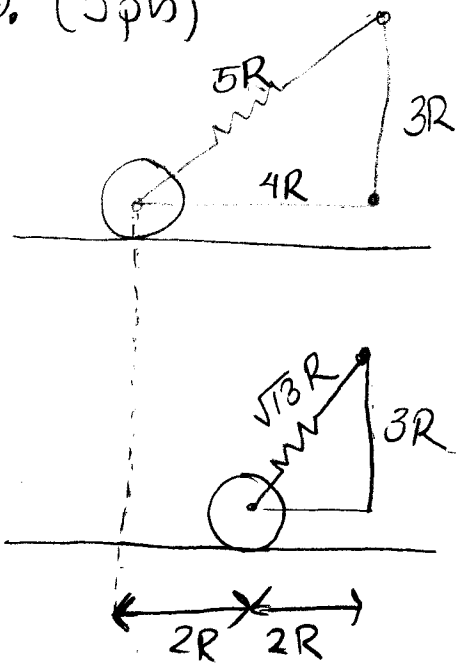
$$-\frac{T\sqrt{2}}{2} + \mu N = m_c a_{cx}$$

$$N = m_c g - \frac{T\sqrt{2}}{2}$$

$$-\frac{T\sqrt{2}}{2} + \mu \left(m_c g - \frac{T\sqrt{2}}{2} \right) = m_c a_{cx} \Rightarrow \text{use instead of } \textcircled{3} \\ \& \text{ solve for } a_x$$

$$a_{cx} = -.836 \text{ m/s}^2$$

3. (5 pts)



$$t=0: V_i = (3R)^2 \frac{1}{2} K \quad T_i = 0$$

$$\text{At time } t: V_f = (\sqrt{3} - 2)^2 R^2 \frac{1}{2} K = 2.58 R^2 \frac{1}{2} K$$

$$T_f = \frac{1}{2} m V_G^2 + \frac{1}{2} I_G \omega^2$$

$$\text{Energy Balance: } 9 \frac{1}{2} R^2 K = \frac{2.58 R^2 K}{2} + \frac{1}{2} m V_G^2 + \frac{1}{2} I_G \omega^2$$

$$\text{Kinematics: } V_G = -R\omega, \quad I_G = \frac{1}{2} m R^2$$

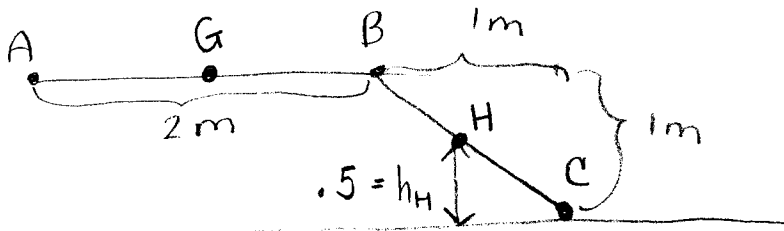
$$9 \frac{1}{2} R^2 K - 2.58 \frac{1}{2} R^2 K = \frac{1}{2} m (-R\omega)^2 + \frac{1}{2} (\frac{1}{2} m R^2) \omega^2$$

$$6.42 K = m\omega^2 + \frac{1}{2} m\omega^2$$

$$6.42 K \cdot \frac{2}{3} = m\omega^2 \Rightarrow \omega^2 = 4.28 K/m$$

$$\boxed{2.07 \sqrt{\frac{K}{m}} = \omega}$$

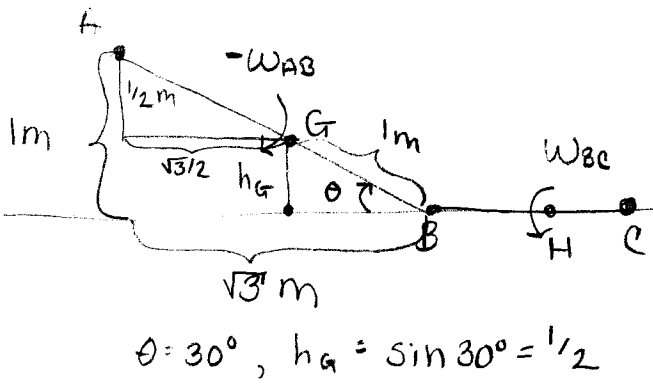
4. (10 pts)



$t=0:$

$$V_i = m_{AB} g h_G + m_{BC} g h_H$$

$$V_i = 5g + 3/2g = \frac{13}{2}g$$



$t:$ (when B hits floor)

$$V_f = m_{AB} g h_G + 0 = 5/2g$$

$$T_f = \frac{1}{2} m_{AB} V_G^2 + \frac{1}{2} I_G \omega_{AB}^2$$

$$+ \frac{1}{2} m_{BC} V_H^2 + \frac{1}{2} I_H \omega_{BC}^2$$

Kinematics

$$\underline{V}_A = 0$$

$$\underline{V}_B = \underline{V}_A + (\underline{\omega}_{AB} \times \underline{r}_{B/A}) = \omega_{AB} \hat{i} + \sqrt{3} \omega_{AB} \hat{j}$$

$$\underline{r}_{B/A} = (\sqrt{3} \hat{i} - \hat{j}) m$$

$$\underline{V}_C = \underline{V}_B + (\underline{\omega}_{BC} \times \underline{r}_{C/B}) = \omega_{AB} \hat{i} + (\sqrt{3} \omega_{AB} + \sqrt{2} \omega_{BC}) \hat{j}$$

$$\underline{r}_{C/B} = \sqrt{2} \hat{i}$$

Constraint: $V_{Cy} = 0 \Rightarrow \sqrt{3} \omega_{AB} + \sqrt{2} \omega_{BC} = 0 \Rightarrow \boxed{\omega_{BC} = -\sqrt{3}/\sqrt{2} \omega_{AB}}$

$$\underline{V}_H = \underline{V}_B + (\underline{\omega}_{BC} \times \underline{r}_{H/B}) = \omega_{AB} \hat{i} + (\sqrt{3} \omega_{AB} + \sqrt{2}/2 \omega_{BC}) \hat{j}$$

$$\underline{r}_{H/B} = \sqrt{2}/2 \hat{i}$$

$$\underline{V}_H = \omega_{AB} \hat{i} + \frac{\sqrt{3}}{2} \omega_{AB} \hat{j}$$

$$\underline{V}_G = \underline{V}_A + \underline{\omega}_{AB} \times \underline{r}_{G/A} = .5 \omega_{AB} \hat{i} + \frac{\sqrt{3}}{2} \omega_{AB} \hat{j}$$

$$|V_H|^2 = (\omega_{AB}^2 + 3/4 \omega_{AB}^2) = 7/4 \omega_{AB}^2$$

$$|V_G|^2 = \left(\frac{1}{2} \omega_{AB}\right)^2 + \left(\frac{\sqrt{3}}{2}\right) \omega_{AB}^2 = \omega_{AB}^2$$

substituting back into Energy

$$I_G = 1/12 m_{AB} L_{AB}^2 = 1/12 m_{AB} 2^2 = \frac{1}{3} m_{AB}$$

$$I_H = 1/12 m_{BC} L_{BC}^2 = 1/12 m_{BC} \cdot 2 = \frac{1}{6} m_{BC}$$

$$T_f = \frac{1}{2} m_{AB} \omega_{AB}^2 + \frac{1}{2} \left(\frac{1}{3} m_{AB}\right) \omega_{AB}^2 + \frac{1}{2} m_{BC} \frac{7}{4} \omega_{AB}^2 + \frac{1}{2} \left(\frac{1}{6} m_{BC}\right) \frac{3}{2} \omega_{AB}^2$$

$$T_f = \frac{1}{2} \omega_{AB}^2 (m_{AB} + 1/3 m_{AB} + 7/4 m_{BC} + 1/4 m_{BC}) = 19/3 \omega_{AB}^2$$

$$V_i = V_f + T_f$$

$$\frac{13}{2} g = \frac{5}{2} g + 19/3 \omega_{AB}^2$$

$$\omega_{AB}^2 = 4g \frac{3}{19} = 6.19$$

$$\omega_{AB} = -2.5 \text{ rad/s}$$

$$\omega_{BC} = 3.0 \text{ rad/s}$$

5. (5pts)

$$W = \cancel{T_f} + \cancel{V_f} - \cancel{T_i} - \cancel{V_i}$$

$$W = 1/2 I_G \omega^2 = 1/2 (1/2 \cdot 6 \cdot (.05)^2) \cdot 10^2$$

$$W = 0.375 \text{ J}$$