

Physics 206.
Homework #2

14.3.2 1). $|\vec{n}+\rangle = \begin{bmatrix} \cos\frac{\theta}{2} e^{-i\varphi/2} \\ \sin\frac{\theta}{2} e^{i\varphi/2} \end{bmatrix}$
 $|\vec{n}-\rangle = \begin{bmatrix} -\sin\frac{\theta}{2} e^{-i\varphi/2} \\ \cos\frac{\theta}{2} e^{i\varphi/2} \end{bmatrix}$

$$\vec{n} \cdot \vec{\sigma} = \frac{1}{2} \begin{bmatrix} \cos\theta & \sin\theta e^{-i\varphi} \\ \sin\theta e^{i\varphi} & -\cos\theta \end{bmatrix}$$

$$\vec{n} \cdot \vec{\sigma} |\vec{n}+\rangle = \frac{1}{2} \begin{bmatrix} \cos\theta & \sin\theta e^{-i\varphi} \\ \sin\theta e^{i\varphi} & -\cos\theta \end{bmatrix} \begin{bmatrix} \cos\frac{\theta}{2} e^{-i\varphi/2} \\ \sin\frac{\theta}{2} e^{i\varphi/2} \end{bmatrix} =$$

$$= \frac{1}{2} \begin{bmatrix} \cos\frac{\theta}{2} \cos\theta e^{-i\varphi/2} + \sin\frac{\theta}{2} \sin\theta e^{-i\varphi} \\ \cos\frac{\theta}{2} \sin\theta e^{i\varphi/2} - \cos\theta \sin\frac{\theta}{2} e^{i\varphi/2} \end{bmatrix} =$$

$$= \frac{1}{2} \begin{bmatrix} \cos(\theta - \frac{\theta}{2}) e^{-i\varphi/2} \\ \sin(\theta - \frac{\theta}{2}) e^{i\varphi/2} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} \cos\frac{\theta}{2} e^{-i\varphi/2} \\ \sin\frac{\theta}{2} e^{i\varphi/2} \end{bmatrix} = \frac{1}{2} |\vec{n}+\rangle$$

$$\langle \vec{n}- | \vec{n}+ \rangle = -\sin\frac{\theta}{2} e^{+i\varphi/2} \cos\frac{\theta}{2} e^{-i\varphi/2} + \cos\frac{\theta}{2} e^{-i\varphi/2} \sin\frac{\theta}{2} e^{i\varphi/2} = 0.$$

Since eigenvectors of $\vec{n} \cdot \vec{\sigma}$ are orthogonal, $|\vec{n}-\rangle$ is the second eigenvector $\Rightarrow \vec{n} \cdot \vec{\sigma} |\vec{n}-\rangle = -\frac{1}{2} |\vec{n}-\rangle$.

2). $\langle \vec{n} \pm | \vec{S} | \vec{n} \pm \rangle = \langle \vec{n} \pm | (\vec{n} \cdot \vec{S}) \vec{n} + (\vec{k} \cdot \vec{S}) \vec{k} + (\vec{l} \cdot \vec{S}) \vec{l} | \vec{n} \pm \rangle$

where $\vec{n}, \vec{k}, \vec{l}$ form a basis.

In the $|\vec{n} \pm \rangle$ basis $(\vec{n} \cdot \vec{S}) = S_z$, $(\vec{k} \cdot \vec{S}) = S_x$, $(\vec{l} \cdot \vec{S}) = S_y$.

$$\langle \vec{n} \pm | \vec{S} | \vec{n} \pm \rangle = \langle \vec{n} \pm | S_z \vec{n} + \vec{k} S_x + \vec{l} S_y | \pm \rangle =$$

$$= \langle \pm | S_z | \pm \rangle \vec{n} \quad (\langle \pm | S_x | \pm \rangle = \langle \pm | S_y | \pm \rangle = 0 \leftarrow \text{diagonal elements})$$

$$\parallel$$

$$\pm \frac{1}{2} \vec{n}.$$

14.3.3.

$$G_z = -i G_x G_y \text{ (and cyclic permutations)} \Rightarrow$$

$$\cancel{A \cdot B} T_z G_z = -i T_z (G_x G_y) \text{ (and permutations)}$$

$$T_z(AB) = T_z(BA) \Rightarrow T_z G_z = \frac{1}{2}(1-i) T_z(G_x G_y + G_y G_x) = \underline{\underline{= -\frac{i}{2} T_z 0 = 0}}$$

14.3.4.

$$\begin{aligned} 1). (\vec{A} \cdot \vec{B})(\vec{B} \cdot \vec{A}) &= \sum A_\alpha B_\alpha B_\beta A_\beta = \sum A_\alpha B_\beta G_\alpha G_\beta = \\ &= \frac{1}{2} \sum A_\alpha B_\beta ([G_\alpha, G_\beta] + [G_\beta, G_\alpha]) = \frac{1}{2} \sum_\alpha A_\alpha B_\alpha [G_\alpha, G_\beta] + \\ &+ \frac{1}{2} \sum_{\alpha \neq \beta} A_\alpha B_\beta [G_\alpha, G_\beta] = (\vec{A} \cdot \vec{B}) + \sum_{\alpha \neq \beta} A_\alpha A_\beta i \epsilon_{\alpha\beta\gamma} G_\gamma = \\ &= (\vec{A} \cdot \vec{B}) + \sum i \epsilon_{\alpha\beta\gamma} A_\alpha A_\beta G_\gamma = (\vec{A} \cdot \vec{B}) + i \vec{B} [\vec{A} \times \vec{B}] \end{aligned}$$

$$\begin{aligned} 2) (\vec{A} \cdot \vec{B})(\vec{B} \cdot \vec{A}) &= \sum m_\alpha G_\alpha \\ m_\beta &= \frac{1}{2} T_z [(\vec{A} \cdot \vec{B})(\vec{B} \cdot \vec{A})] G_\beta \end{aligned}$$

$$m_0 = \frac{1}{2} T_z (\vec{A} \cdot \vec{B})(\vec{B} \cdot \vec{A}) = \frac{1}{2} T_z \sum_{\alpha\beta} A_\alpha B_\beta G_\alpha G_\beta =$$

$$= \frac{1}{2} 2 \sum_\alpha A_\alpha B_\alpha = \vec{A} \cdot \vec{B}$$

$$\begin{aligned} m_{\alpha=x,y,z} &= \frac{1}{2} T_z [(\vec{A} \cdot \vec{B})(\vec{B} \cdot \vec{A}) G_\alpha] = \frac{1}{2} \sum_\beta T_z A_\beta B_\beta G_\beta G_\alpha G_\alpha = \\ &= \frac{1}{2} \sum_{\beta \neq \gamma} T_z A_\beta B_\beta G_\beta G_\gamma G_\alpha = \frac{1}{2} \sum_{\substack{\beta \neq \gamma \\ \delta}} T_z A_\beta B_\beta i \epsilon_{\beta\gamma\delta} G_\delta G_\alpha = \\ &= \sum_{\beta\gamma\delta} \delta_{\alpha\delta} A_\beta B_\beta i \epsilon_{\beta\gamma\delta} = \sum_{\beta\gamma} i \epsilon_{\alpha\beta\gamma} A_\beta B_\gamma = i [\vec{A} \times \vec{B}]_\alpha \end{aligned}$$

14.3.7.

$$1). \sqrt{I + i G_x} = \sqrt{a(I \cos \frac{\theta}{2} - i \sin \frac{\theta}{2} \vec{n} \cdot \vec{G})}$$

$$\vec{n} = \vec{e}_x$$

$$a \cos \frac{\theta}{2} = 1$$

$$-a \sin \frac{\theta}{2} = 1$$

$$\Rightarrow \theta = \frac{\pi}{2} \Rightarrow \cos \frac{\theta}{2} = \frac{1}{\sqrt{2}}, \sin \frac{\theta}{2} = -\frac{1}{\sqrt{2}}, a = \sqrt{2}$$

$$\begin{aligned} \sqrt{I + i G_x} &= \sqrt{\sqrt{2} \exp(-i \frac{\pi}{4} G_x)} = 2^{1/4} \exp(\frac{\pi i}{8} G_x) = \\ &= 2^{1/4} \left[\cos \frac{\pi}{8} + i \sin \frac{\pi}{8} G_x \right] \end{aligned}$$

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$$2) (2I + 6x)^{-1} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}^{-1} = \begin{bmatrix} \frac{2}{2 \cdot 2 - 1 \cdot 1} & -\frac{1}{2 \cdot 2 - 1 \cdot 1} \\ -\frac{1}{2 \cdot 2 - 1 \cdot 1} & \frac{2}{2 \cdot 2 - 1 \cdot 1} \end{bmatrix} = \begin{pmatrix} \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{2}{3} \end{pmatrix} =$$

$$= \frac{2}{3} \hat{I} - \frac{1}{3} \hat{6}_x$$

$$3) 6_x^{-1} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^{-1} = \begin{pmatrix} \frac{0}{0 \cdot 1 - 1 \cdot 1} & -\frac{1}{0 \cdot 1 - 1 \cdot 1} \\ -\frac{1}{0 \cdot 1 - 1 \cdot 1} & \frac{0}{0 \cdot 1 - 1 \cdot 1} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = 6_x //$$

14.4.1.

$$H = -\gamma \vec{L} \cdot \vec{B}$$

$$\frac{d\langle \vec{L} \rangle}{dt} = \frac{d}{dt} \langle \psi(t) | \vec{L} | \psi(t) \rangle = \frac{d}{dt} \langle \psi(0) \exp(\frac{i\hat{H}t}{\hbar}) | \vec{L} | \exp(-\frac{i\hat{H}t}{\hbar}) \psi(0) \rangle = \langle \psi(0) \exp(\frac{i\hat{H}t}{\hbar}) \hat{H} \frac{i}{\hbar} | \vec{L} | \exp(-\frac{i\hat{H}t}{\hbar}) \psi(0) \rangle - \langle \psi(0) \exp(\frac{i\hat{H}t}{\hbar}) | \vec{L} | (-\frac{i\hat{H}}{\hbar}) \exp(-\frac{i\hat{H}t}{\hbar}) \psi(0) \rangle =$$

$$= \frac{i}{\hbar} \langle [\hat{H}, \vec{L}] \rangle$$

$$[H, \vec{L}] = -\gamma [\vec{B} \cdot \vec{L}, \vec{L}] = -\gamma \sum_{\alpha, \beta} B_{\alpha} [L_{\alpha}, L_{\beta}] e_{\beta} =$$

$$= -\gamma \hbar i \sum_{\alpha, \beta, \gamma} B_{\alpha} \epsilon_{\beta\gamma\alpha} L_{\gamma} = -i\gamma \hbar \sum_{\beta, \gamma, \alpha} \epsilon_{\beta\gamma\alpha} \vec{e}_{\beta} L_{\gamma} B_{\alpha} =$$

$$= -i\gamma \hbar [\vec{L} \times \vec{B}]$$

$$\frac{d\langle \vec{L} \rangle}{dt} = \frac{\gamma \hbar}{\hbar} \langle [\vec{L} \times \vec{B}] \rangle = \langle \gamma \vec{L} \rangle \times \vec{B} = \langle \vec{\mu} \rangle \times \vec{B}$$

Our trick is known as the Heisenberg picture.

14.3.8. 1) $[A, \vec{6}] = 0 \Rightarrow [\sum A_{\alpha} \hat{6}_{\alpha}, \vec{6}] = 0 \Rightarrow [A_0 \hat{I}, \vec{6}] +$

$$+ [\sum_{\alpha=x,y,z} A_{\alpha} \hat{6}_{\alpha}, \vec{6}] = 0 \Rightarrow \sum_{\alpha=x,y,z} A_{\alpha} [\hat{6}_{\alpha}, \vec{6}] = 0 \Rightarrow \text{for any } \text{some } \beta$$

$$Tz \sum_{\alpha=x,y,z} A_{\alpha} [\hat{6}_{\alpha}, \hat{6}_{\beta}] = 0 \Rightarrow 2 Tz \sum_{\alpha, \gamma} A_{\alpha} i \epsilon_{\alpha\beta\gamma} \hat{6}_{\gamma} = 0 \Rightarrow$$

$$\Rightarrow 2 \cdot 2 \sum_{\alpha} i A_{\alpha} \epsilon_{\alpha\beta\gamma} = 0 \Rightarrow A_x = A_y = A_z = 0$$

(e.g. $\beta=y, \gamma=z \Rightarrow \sum_{\alpha} A_{\alpha} \epsilon_{\alpha y z} = 0 \Rightarrow A_x = 0$).

2). $A \hat{6}_{\alpha} + \hat{6}_{\alpha} A = 0 \Rightarrow \sum_{\beta=x,y,z} A_{\beta} (\hat{6}_{\beta} \hat{6}_{\alpha} + \hat{6}_{\alpha} \hat{6}_{\beta}) = 0 \Rightarrow Tz \sum_{\beta} A_{\beta} (\hat{6}_{\beta} \hat{6}_{\alpha} + \hat{6}_{\alpha} \hat{6}_{\beta})$

$$= 0 \Rightarrow A_{\alpha} = 0 \text{ for } \alpha=x,y,z \text{ since } Tz(\hat{6}_{\beta} \hat{6}_{\alpha}) = Tz(\hat{6}_{\alpha} \hat{6}_{\beta}) \neq 0 \text{ only for } \alpha=\beta.$$

Thus, $A = A_0 \hat{I}$. However, $A_0 \hat{I} \hat{6}_{\alpha} + \hat{6}_{\alpha} A_0 \hat{I} = 2 A_0 \hat{6}_{\alpha}$. This is equal to zero for $A_0 = 0$ only.

Hence, $A = 0$.

Hw 2-3

14.4.3. $i\hbar \frac{d|\psi(t)\rangle}{dt} = \hat{H}|\psi(t)\rangle$; $|\psi_2(t)\rangle = e^{-i\omega \hat{S}_z t} |\psi(t)\rangle$

$$i\hbar \frac{d|\psi_2(t)\rangle}{dt} = i\hbar \left[-i\omega \hat{S}_z e^{-i\omega \hat{S}_z t} |\psi(t)\rangle + e^{-i\omega \hat{S}_z t} \dot{|\psi(t)\rangle} \right]$$

$$i\hbar |\dot{\psi}_2(t)\rangle = i\hbar \left[-i\omega \hat{S}_z |\psi_2(t)\rangle + e^{-i\omega \hat{S}_z t} (-i\hbar \vec{S} \cdot \vec{B}) \frac{1}{i\hbar} |\psi(t)\rangle \right]$$

$$i\hbar |\dot{\psi}_2(t)\rangle = i\hbar \left[-i\omega \hat{S}_z |\psi_2(t)\rangle + e^{-i\omega \hat{S}_z t} (i\gamma \vec{S} \cdot \vec{B}) e^{+i\omega \hat{S}_z t} e^{-i\omega \hat{S}_z t} |\psi(t)\rangle \right]$$

$$i\hbar |\dot{\psi}_2(t)\rangle = i\hbar \left[-i\omega \hat{S}_z |\psi_2(t)\rangle + e^{-i\omega \hat{S}_z t} (i\gamma \vec{S} \cdot \vec{B}) e^{i\omega \hat{S}_z t} |\psi_2(t)\rangle \right]$$

$$e^{-i\omega \hat{S}_z t} (i\gamma \vec{S} \cdot \vec{B}) e^{i\omega \hat{S}_z t} = i\gamma e^{-i\omega \hat{S}_z t} [B_0 \hat{S}_z + B_x \hat{S}_x \cos \omega t - B_y \hat{S}_y \sin \omega t]$$

$$e^{i\omega \hat{S}_z t} = i\gamma [B_0 \hat{S}_z] + i\gamma e^{-i\omega \hat{S}_z t} [B \hat{S}_x \cos \omega t - B \hat{S}_y \sin \omega t] e^{i\omega \hat{S}_z t} = i\gamma B_0 \hat{S}_z + i\gamma \left(\cos \frac{\omega t}{2} \hat{I} - i \hat{S}_z \sin \frac{\omega t}{2} \right) \times$$

$$\times [\hat{S}_x \cos \omega t - \hat{S}_y \sin \omega t] \left(\cos \frac{\omega t}{2} \hat{I} + 2i \hat{S}_z \sin \frac{\omega t}{2} \right) =$$

$$= i\gamma B_0 \hat{S}_z + i\gamma B \left[\hat{S}_x \cos \omega t \cos \frac{\omega t}{2} + \hat{S}_y \cos \omega t \sin \frac{\omega t}{2} - \hat{S}_y \sin \omega t \cos \frac{\omega t}{2} + \hat{S}_x \sin \omega t \sin \frac{\omega t}{2} \right] \left(\cos \frac{\omega t}{2} \hat{I} + 2i \hat{S}_z \sin \frac{\omega t}{2} \right) =$$

$$= i\gamma B_0 \hat{S}_z + i\gamma B \left[\hat{S}_x \cos \frac{\omega t}{2} - \hat{S}_y \sin \frac{\omega t}{2} \right] \left[\cos \frac{\omega t}{2} \hat{I} + 2i \hat{S}_z \sin \frac{\omega t}{2} \right]$$

$$= i\gamma B_0 \hat{S}_z + i\gamma B \left[\hat{S}_x \cos^2 \frac{\omega t}{2} - \hat{S}_y \sin \frac{\omega t}{2} \cos \frac{\omega t}{2} + \hat{S}_y \cos \frac{\omega t}{2} \sin \frac{\omega t}{2} + \hat{S}_x \sin^2 \frac{\omega t}{2} \right] = i\gamma B_0 \hat{S}_z + i\gamma B \hat{S}_x$$

$$i\hbar |\dot{\psi}_2\rangle = i\hbar [-i\omega \hat{S}_z + i\gamma B_0 \hat{S}_z + i\gamma B \hat{S}_x] |\psi_2\rangle$$

$$i\dot{\psi}_2 = [i(\gamma B_0 - \omega) \hat{S}_z + i\gamma B \hat{S}_x] |\psi_2\rangle$$

$$U_2(t) = \exp [i(\gamma B_0 - \omega) \hat{S}_z t + i\gamma B \hat{S}_x t] =$$

$$= \exp [i\omega_2 t \left(\frac{\gamma B_0 - \omega}{\omega_2} \hat{S}_z + \frac{\gamma B}{\omega_2} \hat{S}_x \right)] =$$

$$= \cos \frac{\omega_2 t}{2} \hat{I} + 2i \left(\frac{\gamma B_0 - \omega}{\omega_2} \hat{S}_z + \frac{\gamma B}{\omega_2} \hat{S}_x \right) \sin \frac{\omega_2 t}{2} =$$

$$= \cos \frac{\omega_2 t}{2} \hat{I} + 2i \left(\frac{\omega_0 - \omega}{\omega_2} \hat{S}_z + \frac{\gamma B}{\omega_2} \hat{S}_x \right) \sin \frac{\omega_2 t}{2}$$

$$|\psi(t)\rangle = \begin{pmatrix} e^{+i\omega t/2} & 0 \\ 0 & e^{-i\omega t/2} \end{pmatrix} |\psi_2(t)\rangle =$$

$$= \begin{pmatrix} e^{i\omega t/2} & 0 \\ 0 & e^{-i\omega t/2} \end{pmatrix} \begin{bmatrix} \cos \frac{\omega_2 t}{2} + i \frac{\omega_0 - \omega}{\omega_2} \sin \frac{\omega_2 t}{2} & i \frac{\gamma B}{\omega_2} \sin \frac{\omega_2 t}{2} \\ i \frac{\gamma B}{\omega_2} \sin \frac{\omega_2 t}{2} & \cos \frac{\omega_2 t}{2} - i \frac{\omega_0 - \omega}{\omega_2} \sin \frac{\omega_2 t}{2} \end{bmatrix}$$

$$\times |\psi(0)\rangle = \begin{bmatrix} e^{i\omega t/2} \left[\cos \frac{\omega_2 t}{2} + i \frac{\omega_0 - \omega}{\omega_2} \sin \frac{\omega_2 t}{2} \right] \\ e^{-i\omega t/2} i \frac{\gamma B}{\omega_2} \sin \frac{\omega_2 t}{2} \end{bmatrix}$$

At $\omega_0 = \omega$

$$\psi(t) = \begin{bmatrix} e^{i\omega t/2} \cos \frac{\omega_2 t}{2} \\ e^{-i\omega t/2} i \frac{\gamma B}{\omega_2} \sin \frac{\omega_2 t}{2} \end{bmatrix}$$

$$\omega_2 = \gamma \sqrt{B^2 + \left(\frac{\omega_0}{\gamma} - \frac{\omega}{\gamma}\right)^2} = \gamma B \Rightarrow$$

$$\psi(t) = \begin{bmatrix} e^{i\omega t/2} \cos \frac{\omega_2 t}{2} \\ i e^{-i\omega t/2} \sin \frac{\omega_2 t}{2} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} e^{i\omega t/2 - \frac{\pi}{4}} \cos \frac{\omega_2 t}{2} \\ e^{-i\omega t/2 + \frac{\pi}{4}} \sin \frac{\omega_2 t}{2} \end{bmatrix}$$

$|\vec{n}_+\rangle$ state

$$\mu_z = \frac{1}{2} [|\psi_\uparrow(t)|^2 - |\psi_\downarrow(t)|^2] =$$

$$= \frac{1}{2} \left[\cos^2 \frac{\omega_2 t}{2} + \left(\frac{\omega_0 - \omega}{\omega_2} \right)^2 \sin^2 \frac{\omega_2 t}{2} - \frac{\gamma^2 B^2}{\omega_2^2} \sin^2 \frac{\omega_2 t}{2} \right] =$$

$$= \frac{1}{2} \left[\left(\frac{\omega_0 - \omega}{\omega_2} \right)^2 - \frac{\gamma^2 B^2}{\omega_2^2} \sin^2 \frac{\omega_2 t}{2} + \cos^2 \frac{\omega_2 t}{2} \left(1 - \frac{(\omega_0 - \omega)^2}{\gamma^2 B^2 + (\omega_0 - \omega)^2} \right) \right] =$$

$$= \mu_z(0) \left[\frac{(\omega_0 - \omega)^2}{(\omega_0 - \omega)^2 + \gamma^2 B^2} + \frac{\gamma^2 B^2 (\cos^2 \frac{\omega_2 t}{2} - \sin^2 \frac{\omega_2 t}{2})}{(\omega_0 - \omega)^2 + \gamma^2 B^2} \right] =$$

$$= \mu_z(0) \left[\frac{(\omega_0 - \omega)^2}{(\omega_0 - \omega)^2 + \gamma^2 B^2} + \frac{\gamma^2 B^2 \cos \omega_2 t}{(\omega_0 - \omega)^2 + \gamma^2 B^2} \right] //$$

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14.4.4. $\omega = \gamma B = \frac{eB}{mc}$. Flip means $\Delta\theta = \pi$.

$$\Delta\theta = \omega t \Rightarrow t = \frac{\pi mc}{eB} \approx \frac{3 \cdot 10^{-27} \cdot 3 \cdot 10^{10} \frac{\text{cm}}{\text{s}}}{5 \cdot 10^{-10} \text{ cgs } 10^2} \approx$$

$$\approx 2 \cdot \frac{10^{-17}}{10^{-8}} \text{ s} = 2 \cdot 10^{-9} \text{ s}.$$

3.4. $\hat{S}_z(\hat{S}_z + 1)(\hat{S}_z - 1)|\psi\rangle = \hat{S}_z(\hat{S}_z + 1)(\hat{S}_z - 1) \sum_{i=-1,0,1} \alpha_i |\psi_i\rangle$

where $\hat{S}_z |\psi_k\rangle = k |\psi_k\rangle$.

$\hat{S}_z |\psi_0\rangle = 0$; $(\hat{S}_z + 1)|\psi_{-1}\rangle = 0$; $(\hat{S}_z - 1)|\psi_1\rangle = 0$.

Hence, $\hat{S}_z(\hat{S}_z + 1)(\hat{S}_z - 1) = 0$.

$\hat{S}_z$ and $\hat{S}_x$ are equivalent.

Hence, $\hat{S}_z(\hat{S}_x + 1)(\hat{S}_x - 1) = 0$.