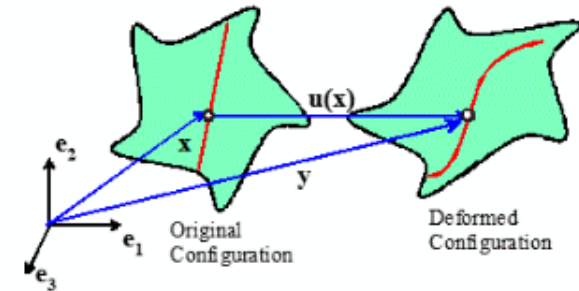


# Review

Deformation Mapping  $y_i = x_i + u_i(x_1, x_2, x_3, t)$



## Eulerian/Lagrangian descriptions of motion

$$y_i = x_i + u_i(x_j, t) \quad \left. \frac{\partial y_i}{\partial t} \right|_{x_i = \text{const}} = \frac{\partial u_i}{\partial t} = v_i(x_j, t)$$

$$y_i = x_i + u_i(y_j, t) \quad \left. \frac{\partial y_i}{\partial t} \right|_{x_i = \text{const}} = v_i(y_j, t) \quad \left. \frac{\partial^2 y_i}{\partial t^2} \right|_{x_i = \text{const}} = a_i(y_j, t)$$

$$\left( \delta_{ik} - \frac{\partial u_i}{\partial y_k} \right) \left. \frac{\partial y_k}{\partial t} \right|_{x_i = \text{const}} = \left. \frac{\partial u_i}{\partial t} \right|_{y_i = \text{const}} \quad \left. \frac{\partial^2 y_i}{\partial t^2} \right|_{x_i = \text{const}} = a_i(y_j, t) = \left. \frac{\partial v_i}{\partial t} \right|_{y_i = \text{const}} + v_k(y_j, t) \frac{\partial v_i}{\partial y_k}$$

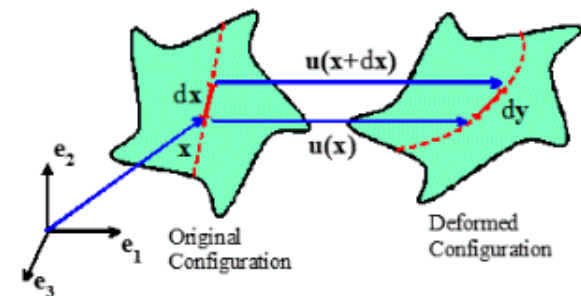
## Deformation Gradient

$$\nabla \mathbf{y} = \nabla (\mathbf{x} + \mathbf{u}(\mathbf{x})) = \mathbf{F}$$

or  $\frac{\partial y_i}{\partial x_j} = \frac{\partial}{\partial x_j} (x_i + u_i) = \delta_{ij} + \frac{\partial u_i}{\partial x_j} = F_{ij}$

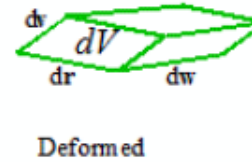
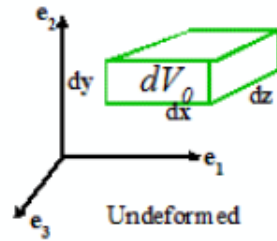
$$d\mathbf{y} = \mathbf{F} \cdot d\mathbf{x}$$

$$dy_i = F_{ik} dx_k$$



Jacobian

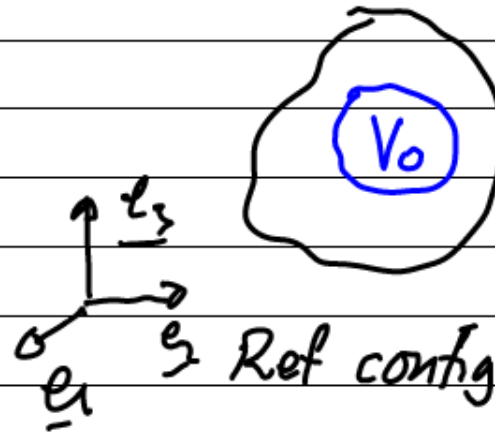
$$J = \det(\mathbf{F}) = \frac{dV}{dV_0}$$



### Useful Observation

$$\int_V \phi dV = \int_{V_0} \phi J dV_0$$

$\phi$  - any scalar function of  $\underline{x}$  or  $\underline{y}$



## Area Elements

$$dA \underline{n} = J F^{-T} dA_0 \underline{n}_0$$

Proof: Let  $d\underline{x}$ ,  $d\underline{y}$  be two fibers passing through a pt

$$\text{Let } d\underline{v} = F d\underline{x} \quad d\underline{w} = F d\underline{y} \quad dA \underline{n} = d\underline{v} \times d\underline{w}$$

$$dA n_i = \epsilon_{ijk} dv_j dw_k = \epsilon_{ijk} F_{jp} dx_p F_{kq} dy_q$$

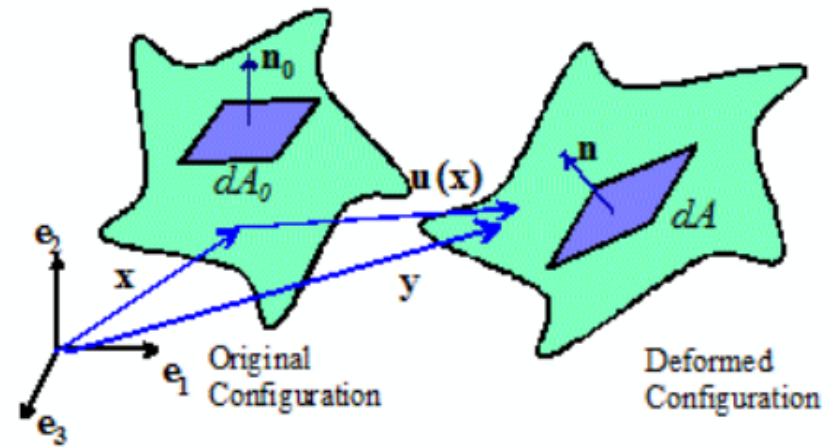
$$= F_{ri} \epsilon_{rjnk} F_{nr} F_{jp} F_{kq} dx_p dy_q$$

$$= F_{ri}^{-1} \epsilon_{rpq} \det(F) dx_p dy_q$$

$$F_{nr} F_{ri}^{-1} = \delta_{in}$$

$$A^T B = C_{ij} = J F_{ri}^{-1} \epsilon_{rpq} dx_p dy_q = J F^{-T} dA_0 \underline{n}_0$$

$$A_{ki} B_{kj} = C_{ij}$$



Line Elements

## Lagrange Strain Tensor

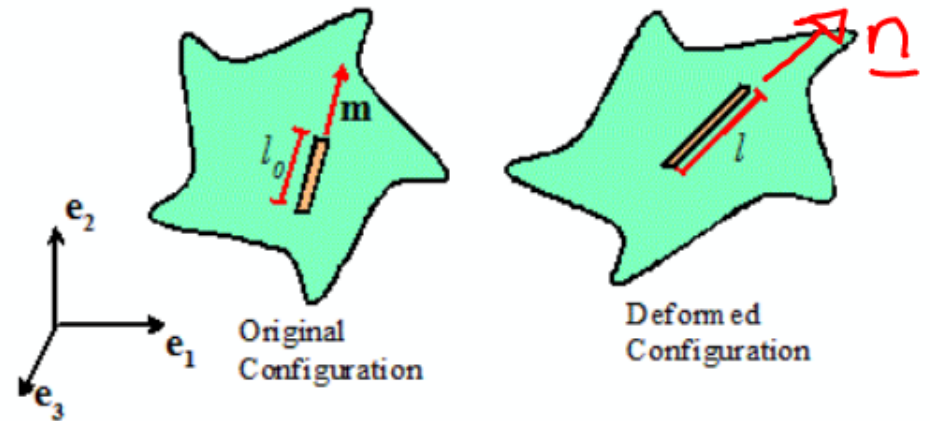
$$\underline{E} = \frac{1}{2} (\underline{F}^T \underline{F} - \underline{I})$$

$$E_{ij} = \frac{1}{2} (F_{ki} F_{kj} - \delta_{ij})$$

$$\frac{l^2 - l_0^2}{2l_0^2} = \underline{m} \cdot \underline{E} \underline{m} = m_i E_{ij} m_j$$

Proof:  $\underline{dy} = \underline{l} \underline{n}$        $\underline{dx} = l_0 \underline{m}$

$$\begin{aligned} l^2 - l_0^2 &= \underline{dy} \cdot \underline{dy} - \underline{dx} \cdot \underline{dx} = (\underline{F} \underline{dx}) \cdot \underline{F} \underline{dx} - \underline{dx} \cdot \underline{dx} \\ &= \underline{dx} \cdot (\underline{F}^T \underline{F} - \underline{I}) \underline{dx} \\ &= l_0 \underline{m} \cdot (2\underline{E}) l_0 \underline{m} \end{aligned} \quad \text{Q.E.D.}$$



## Left and Right Cauchy - Green Strain tensors

\* Right Cauchy - Green tensor  $C = F^T F$

\* Left " " " "  $B = F F^T$

$$\frac{\ell^2}{\ell_0^2} = \underline{n} \cdot C \underline{n} \qquad \frac{\ell_0^2}{\ell^2} = \underline{n} \cdot B^{-1} \underline{n}$$

## Eulerian strain tensor

$$E^* = \frac{1}{2} (I - F^{-T} F^{-1})$$

$$\frac{\ell^2 - \ell_0^2}{2\ell^2} = \underline{n} \cdot E^* \underline{n}$$

$$\text{Let } E = \begin{bmatrix} E_{11} & E_{12} \\ E_{12} & E_{22} \end{bmatrix}$$

$$\underline{m}^1 = (1 \ 0)$$

$$\underline{m}^2 = (-\frac{1}{2} \ \frac{\sqrt{3}}{2})$$

$$\underline{m}^3 = (\frac{1}{2} \ \frac{\sqrt{3}}{2})$$

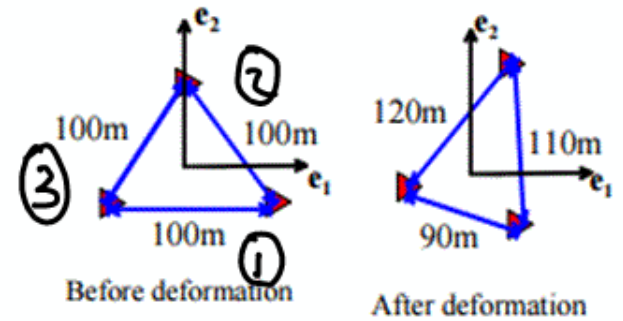
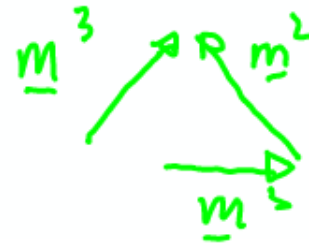
$$\underline{m}^1 \cdot E \underline{m}^1 = (1 \ 0) \begin{bmatrix} E_{11} & E_{12} \\ E_{12} & E_{22} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = E_{11} = \frac{90^2 - 100^2}{2 \cdot 100^2}$$

$$\underline{m}^2 \cdot E \underline{m}^2 = \begin{bmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} E_{11} & E_{12} \\ E_{12} & E_{11} \end{bmatrix} \begin{bmatrix} -\frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{bmatrix} = \frac{E_{11}}{4} + \frac{3E_{22}}{4} - \frac{\sqrt{3}}{2} E_{12} = \frac{110^2 - 100^2}{2 \cdot 100^2}$$

$$\underline{m}^3 \cdot E \underline{m}^3 = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} E_{11} & E_{12} \\ E_{12} & E_{11} \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{bmatrix} = \frac{E_{11}}{4} + \frac{3E_{22}}{4} + \frac{\sqrt{3}}{2} E_{12} = \frac{120^2 - 100^2}{2 \cdot 100^2}$$

Example

Find the Lagrange Strain:



$$E_{11} = -\frac{19}{200}$$

$$E_{22} = \frac{149}{600}$$

$$E_{33} = \frac{23\sqrt{3}}{600}$$

## Polar Decomposition of F

Polar decomposition theorem :  $F = RU = VR$

$U = U^T$  - Right stretch tensor

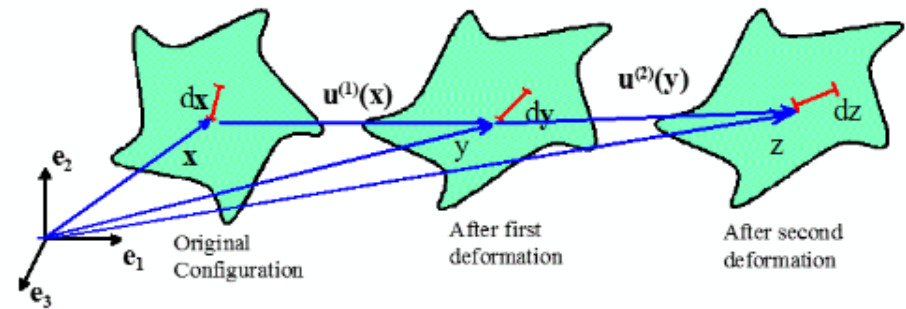
$V = V^T$  - Left " "

$RR^T = R^T R$  - Rotation tensor

## Visualization

①  $F = F^{(2)} F^{(1)}$  is a sequence of two deformations

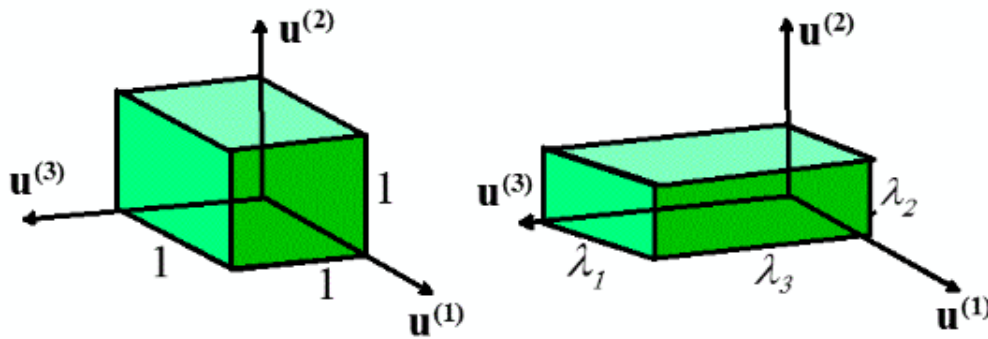
$$dz = F^{(2)} dy = F^{(2)} F^{(1)} dx$$



- ②  $R$  is a rigid rotation : preserves lengths and angles
- ③  $U$  and  $V$  can be visualized using their eigenvalues & eigenvectors

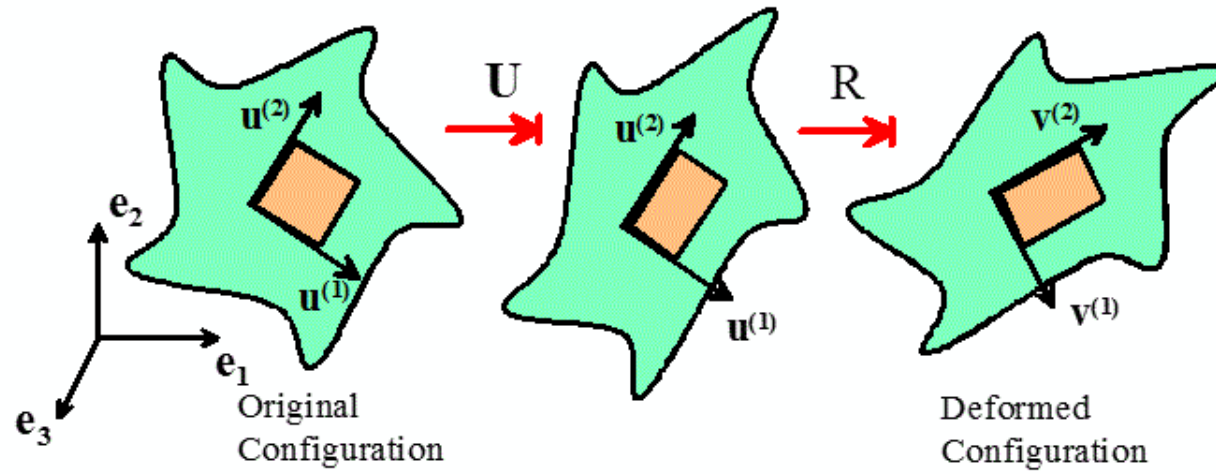
eg let  $\{ \lambda_i \underline{u}^{(i)} \}$  satisfy  $U \underline{u}^{(i)} = \lambda_i \underline{u}^{(i)}$  with  $\underline{u}^{(i)} \cdot \underline{u}^{(j)} = \delta_{ij}$

$\Rightarrow$  material fibers parallel to  $\underline{u}^{(i)}$  remain parallel to  $\underline{u}^{(i)}$  but increase in length by a factor  $\lambda_i$





Hence visualize  $F = RU$  as below



Similarly :  $F = VR$  is a rigid rotation followed by stretches parallel to principal axes of  $V$

$\lambda_i$  : Principal stretches  
 $u^{(i)}, v^{(i)}$  = principal stretch directions